

# imajbox<sup>®</sup> 360

## ACCURATE 3D MAPPING FROM 360° IMAGERY

imajbox<sup>®</sup> 360 is a standalone mobile mapping system producing 3D data from 360° imagery.

### Designed to be efficient on all aspects:



#### Simple

Safe and quick mounting system for any vehicle. Setup in a minute, no cabling. One person to operate, Full remote control from any smartphone.



#### Accurate

High accuracy positioning platform combining GPS, GLONASS, GALILEO, BEIDU multifrequency GNSS receiver, 6 axis high end IMU, and IMAJING InertialVision fusion algorithms. Supports RTK and PPK positioning for sub-centimetric accuracy.



#### Productive

High capacity extractible storage, operating standalone on battery for 2h or power supply with a simple cigarette lighter socket. Full auto-calibration and continuous acquisition for large scale coverage and up to 130km/h.

### Applications:

- MAPPING, INVENTORY
- MONITORING, CHANGE DETECTION
- WORK CONTROL
- IMMERSIVE VIRTUAL VISIT
- SMART CITY
- PAVEMENT MANAGEMENT

### All-in-one and ready to survey

Fast setup, no cabling.  
1 minut to be ready to survey.  
All included capture system, with battery, storage and WiFi remote control.

**Delivered in a fly case and ready to use.**

**CMOS global shutter image sensor** 30MPX Panorama (equirectangular)  
12 bits acquisition  
Auto shutter  
Auto white balance

**Auto-trigger** Inter distance configurable  
from 1m to 10m between panoramas

**Resolution** 8192x4096 pixels

**Deep depth of field** Sharp from 0,5 to 100m from camera

**HFOV** 360°

**Maximum frame rate** 10fps

**High end IMU 6 axis MEMS IMU DX4**  
**Gyroscopes:**  
Dynamic range:  $\pm 480^\circ/s$   
In-run bias stability:  $6.25^\circ/hr$   
Angular random walk:  $0.3/\sqrt{hr}$

**Accelerometers:**  
Dynamic range:  $\pm 18g$   
In-run bias stability:  $0,1mg$   
Velocity random walk:  $0.029m/sec/\sqrt{hr}$

**Real time GNSS (NTRIP corrections)** Standalone, SBAS, DGNSS, RTK

**Post Processed GNSS (RINEX corrections)** Standalone, SBAS, DGNSS, PPK

**GNSS tracked frequencies**  
GPS (L1, L2, L5)  
GLONASS (L1, L2, L3)  
Galileo (E1, E5a, E5b, AltBoc)  
BeiDou (B1, B2)  
SBAS (EGNOS, WAAS, GAGAN, MSAS, SDCM)  
QZSS (L1, L2, L5)

**Positioning platform (DRMS)** Accuracy X, Y: 0,01m  
Accuracy Z: 0,02m

## HARDWARE

<b>Housing</b>	Aluminium
<b>Weight</b>	11 kg (imajbox®) 9kg (roof mounting system)
<b>Size</b>	36x36x52cm
<b>Connectivity</b>	USB 3 / Ethernet / Wi-Fi host (for web remote control) Wi-Fi client (for corrections)
<b>Operational limits</b>	-10°C to +40°C
<b>Protection level</b>	IP 65
<b>Internal battery</b>	2 hours
<b>Power supply</b>	12 V / A
<b>Survey speed</b>	Up to 130 km/h
<b>Storage</b>	1TB extractible SSD

## SOFTWARE

**Desktop software** (not included): imajview 5

**Included post processing softwares**  
imajing browser  
Kinematic post processing module (PPK)  
imajing InertialVision fusion algorithms

## ALL-INCLUDED PACKAGE

- ▶ Delivered in a fly case including the unit, the car roof mounting system, external power supply cables and post-processing softwares.

